

Homework #3

1.

(a)

$$\text{Jacobian: } \mathbf{J} = \begin{bmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial s} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial s} \end{bmatrix}$$

The coordinates of any point inside the element are interpolated from:

$$\begin{cases} x = \sum_{i=1}^4 h_i(r,s)x_i \\ y = \sum_{i=1}^4 h_i(r,s)y_i \end{cases} \quad \text{with,} \quad \begin{cases} h_1 = \frac{1}{4}(1+r)(1+s) \\ h_2 = \frac{1}{4}(1-r)(1+s) \\ h_3 = \frac{1}{4}(1-r)(1-s) \\ h_4 = \frac{1}{4}(1+r)(1-s) \end{cases}$$

$$(x_i, y_i) = \{(3, 3), (-5, 5), (-3, -3), (2, -1)\}$$

Derivatives of Shape Functions with respect to r and s :

$$\rightarrow \begin{cases} \frac{\partial h_1}{\partial r} = \frac{1}{4}(1+s) \\ \frac{\partial h_2}{\partial r} = -\frac{1}{4}(1+s) \\ \frac{\partial h_3}{\partial r} = -\frac{1}{4}(1-s) \\ \frac{\partial h_4}{\partial r} = \frac{1}{4}(1-s) \end{cases} \quad \text{and} \quad \begin{cases} \frac{\partial h_1}{\partial s} = \frac{1}{4}(1+r) \\ \frac{\partial h_2}{\partial s} = \frac{1}{4}(1-r) \\ \frac{\partial h_3}{\partial s} = -\frac{1}{4}(1-r) \\ \frac{\partial h_4}{\partial s} = -\frac{1}{4}(1+r) \end{cases}$$

Derivatives of Shape Functions at $(r = s = 0)$

$$\rightarrow \begin{cases} \frac{\partial h_1}{\partial r} = \frac{1}{4} \\ \frac{\partial h_2}{\partial r} = -\frac{1}{4} \\ \frac{\partial h_3}{\partial r} = -\frac{1}{4} \\ \frac{\partial h_4}{\partial r} = \frac{1}{4} \end{cases} \quad \begin{cases} \frac{\partial h_1}{\partial s} = \frac{1}{4} \\ \frac{\partial h_2}{\partial s} = \frac{1}{4} \\ \frac{\partial h_3}{\partial s} = -\frac{1}{4} \\ \frac{\partial h_4}{\partial s} = -\frac{1}{4} \end{cases}$$

$$\rightarrow \mathbf{J}(0, 0) = \begin{bmatrix} \sum_{i=1}^4 \frac{\partial h_i}{\partial r} x_i & \sum_{i=1}^4 \frac{\partial h_i}{\partial r} y_i \\ \sum_{i=1}^4 \frac{\partial h_i}{\partial s} x_i & \sum_{i=1}^4 \frac{\partial h_i}{\partial s} y_i \end{bmatrix} = \begin{bmatrix} \frac{13}{4} & 0 \\ -\frac{1}{4} & 3 \end{bmatrix}$$

(b)

$$\mathbf{J}^{-1} \begin{bmatrix} \frac{\partial h_1}{\partial r} & \frac{\partial h_2}{\partial r} & \frac{\partial h_3}{\partial r} & \frac{\partial h_4}{\partial r} \\ \frac{\partial h_1}{\partial s} & \frac{\partial h_2}{\partial s} & \frac{\partial h_3}{\partial s} & \frac{\partial h_4}{\partial s} \end{bmatrix} = \begin{bmatrix} a_1 & a_2 & a_3 & a_4 \\ b_1 & b_2 & b_3 & b_4 \end{bmatrix} \rightarrow \mathbf{B} = \begin{bmatrix} a_1 & a_2 & a_3 & a_4 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & b_1 & b_2 & b_3 & b_4 \\ b_1 & b_2 & b_3 & b_4 & a_1 & a_2 & a_3 & a_4 \end{bmatrix}$$

$$\therefore \mathbf{J}_{(0,0)}^{-1} \begin{bmatrix} \frac{\partial h_i}{\partial r}(0,0) \\ \frac{\partial h_i}{\partial s}(0,0) \end{bmatrix} = \frac{4}{39} \begin{bmatrix} 3 & 0 \\ \frac{1}{4} & \frac{13}{4} \end{bmatrix} \begin{bmatrix} \frac{1}{4} & -\frac{1}{4} & -\frac{1}{4} & \frac{1}{4} \\ \frac{1}{4} & \frac{1}{4} & -\frac{1}{4} & -\frac{1}{4} \end{bmatrix} = \frac{1}{39} \begin{bmatrix} 3 & -3 & -3 & 3 \\ \frac{7}{2} & 3 & -\frac{7}{3} & -3 \end{bmatrix}$$

$$\mathbf{B}(0,0) = \frac{1}{39} \begin{bmatrix} 3 & -3 & -3 & 3 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{7}{2} & 3 & -\frac{7}{2} & -3 \\ \frac{7}{2} & 3 & -\frac{7}{2} & -3 & 3 & -3 & -3 & 3 \end{bmatrix}$$

(c)

$$K_{u_1 v_1} = t \int_{-1}^1 \int_{-1}^1 \mathbf{B}(:,1)^T \mathbf{C} \mathbf{B}(:,5) \det(\mathbf{J}) \, dr \, ds$$

Gaussian integration:

$$\begin{aligned} \rightarrow K_{u_1 v_1} &= t w_r w_s \mathbf{B}_{(:,1)}^T(0,0) \mathbf{C} \mathbf{B}_{(:,5)}(0,0) \det(\mathbf{J}(0,0)) \\ &= 1 \times 4 \times \frac{1}{39} \begin{bmatrix} 3 & 0 & \frac{7}{2} \end{bmatrix} \begin{bmatrix} E & 0 & 0 \\ 0 & E & 0 \\ 0 & 0 & E/2 \end{bmatrix} \frac{1}{39} \begin{bmatrix} 0 \\ \frac{7}{2} \\ 3 \end{bmatrix} \times \frac{39}{4} \\ &= \frac{E}{78} \begin{bmatrix} 3 & 0 & \frac{7}{4} \end{bmatrix} \begin{bmatrix} 0 \\ \frac{7}{2} \\ 3 \end{bmatrix} = \frac{7}{52} E \end{aligned}$$

2.

(a)

$$\begin{cases} h_1 = r \\ h_2 = s \\ h_3 = 1 - r - s \end{cases} \rightarrow \begin{cases} \frac{\partial h_1}{\partial r} = 1 & \frac{\partial h_1}{\partial s} = 0 \\ \frac{\partial h_2}{\partial r} = 0 & \frac{\partial h_2}{\partial s} = 1 \\ \frac{\partial h_3}{\partial r} = -1 & \frac{\partial h_3}{\partial s} = -1 \end{cases}$$

$$(x_i, y_i) = \{(20, 3), (0, 10), (0, 0)\}$$

$$\mathbf{J} = \begin{bmatrix} \sum_{i=1}^3 \frac{\partial h_i}{\partial r} x_i & \sum_{i=1}^3 \frac{\partial h_i}{\partial r} y_i \\ \sum_{i=1}^3 \frac{\partial h_i}{\partial s} x_i & \sum_{i=1}^3 \frac{\partial h_i}{\partial s} y_i \end{bmatrix} = \begin{bmatrix} 20 & 0 \\ 0 & 10 \end{bmatrix}$$

(b)

$$\mathbf{J}^{-1} \begin{bmatrix} \frac{\partial h_1}{\partial r} & \frac{\partial h_2}{\partial r} & \frac{\partial h_3}{\partial r} \\ \frac{\partial h_1}{\partial s} & \frac{\partial h_2}{\partial s} & \frac{\partial h_3}{\partial s} \end{bmatrix} = \frac{1}{200} \begin{bmatrix} 10 & 0 \\ 0 & 20 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \end{bmatrix} = \frac{1}{200} \begin{bmatrix} 10 & 0 & -10 \\ 0 & 20 & -20 \end{bmatrix}$$

$$\text{Local } \mathbf{B} : \mathbf{B}^{(1)} = \frac{1}{200} \begin{bmatrix} 10 & 0 & -10 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 20 & -20 \\ 0 & 20 & -20 & 10 & 0 & -10 \end{bmatrix}$$

$$\text{Global } \mathbf{B} : \mathbf{B} = \frac{1}{200} \begin{bmatrix} 10 & 0 \\ 0 & 0 \\ 0 & 10 \end{bmatrix}$$

(c)

Gauss integration:

$$\begin{aligned} \mathbf{K} &= \int_V \mathbf{B}^T \mathbf{C} \mathbf{B} \det(\mathbf{J}) \, dV \\ &= \frac{1}{2} t \sum_{i=1}^3 \mathbf{B}^T(r_i, s_i) \mathbf{C} \mathbf{B}(r_i, s_i) \det(\mathbf{J}(r_i, s_i)) \cdot \omega_i \\ &= \frac{1}{2} t \sum_{i=1}^3 \frac{1}{200} \begin{bmatrix} 10 & 0 & 0 \\ 0 & 0 & 10 \end{bmatrix} \begin{bmatrix} E & 0 & 0 \\ 0 & E & 0 \\ 0 & 0 & E/2 \end{bmatrix} \frac{1}{200} \begin{bmatrix} 10 & 0 \\ 0 & 0 \\ 0 & 10 \end{bmatrix} \cdot 200 \cdot \omega_i \\ &= \frac{E}{400} \left\{ \frac{1}{3} \begin{bmatrix} 100 & 0 \\ 0 & 50 \end{bmatrix} + \frac{1}{3} \begin{bmatrix} 100 & 0 \\ 0 & 50 \end{bmatrix} + \frac{1}{3} \begin{bmatrix} 100 & 0 \\ 0 & 50 \end{bmatrix} \right\} = E \begin{bmatrix} 1/4 & 0 \\ 0 & 1/8 \end{bmatrix} \end{aligned}$$

Direct integration:

$$\mathbf{K} = t \int_0^1 \int_0^{1-r} \mathbf{B}^T \mathbf{C} \mathbf{B} \det(\mathbf{J}) \, ds \, dr = \frac{E}{200} \int_0^1 \int_0^{1-r} \begin{bmatrix} 100 & 0 \\ 0 & 50 \end{bmatrix} \, ds \, dr = \frac{E}{200} \begin{bmatrix} 100 & 0 \\ 0 & 50 \end{bmatrix} \int_0^1 (1-r) \, dr = E \begin{bmatrix} 1/4 & 0 \\ 0 & 1/8 \end{bmatrix}$$